

Team Members


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Research and Development of a Hybrid Powered Unmanned Aerial Vehicle (UAV)




Objective: To develop a UAV equipped with a hybrid energy system that is capable of switching between battery and gas generator power midflight.

Initial UAV Setup and Testing




Sizing Study

Weight Budget Distribution

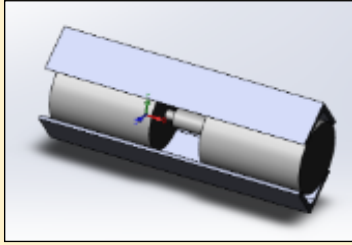


Drone frame	ESC	Prop motor	Propeller
Battery	Koford motor	Koford controllers	Fuel tank
Fuel (1 gram)	Trackstar engine	Misc.	Unused

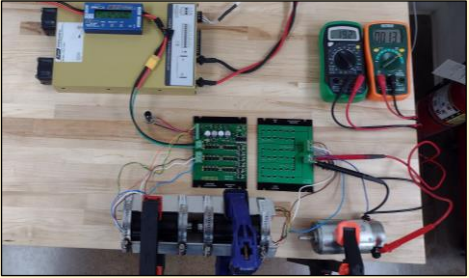
Genset Part Selection



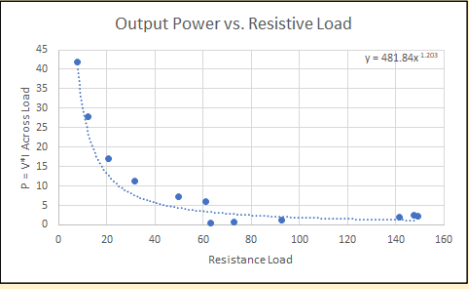
Genset Bench Test Modeling via Solidworks



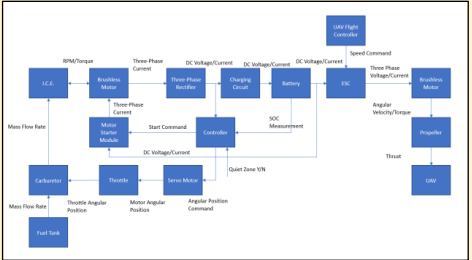
Genset Bench Test Assembly/Testing



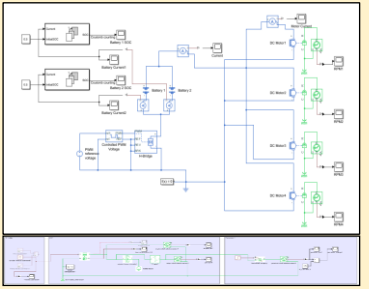
Genset Bench Test Results



Benchtop Hybrid Engine Block Diagram



Genset Modeling via Simulink



Results: The team successfully implemented a genset for the hybrid UAV and observed a nonlinear response of power with a variable load input.

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Faculty Advisor
Dr. Mitch Wolff

